

Simulating Space Use of Animals from RSF and SSF

Johannes Signer (🐦 [signer_j](#))

Wildlife Sciences, Georg-August-Universität Göttingen
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Problem: How to quantify and predict space use by animals?

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2. How to obtain accurate estimates of space use?
3. Is it possible to predict space use of animals in novel or altered landscapes?

Why not use home ranges?

- Traditional home-range concept¹ is complex and nontrivial to quantify.

¹Burt, W. (1943). Territoriality and home range concepts as applied to mammals. *Journal of mammalogy*, 24(3), 346-352.

²Signer, J. et al. (2017). Estimating utilization distributions from fitted step-selection functions. *Ecosphere*, 8(4), e01771.

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- Most home range estimators do not provide a mechanistic model linking space use to habitat characteristics and movement → prediction.
- Simulations from integrated Step Selection Functions (iSSFs) are an interesting alternative to home ranges to quantify space use².

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Integrated Step Selection Functions (iSSFs)

- Estimate distribution for step lengths and turning angles.
- Pair each observed step with J random steps.
- Extract covariate values at the end of each step.
- Estimate selection coefficients β with a conditional logistic regression.

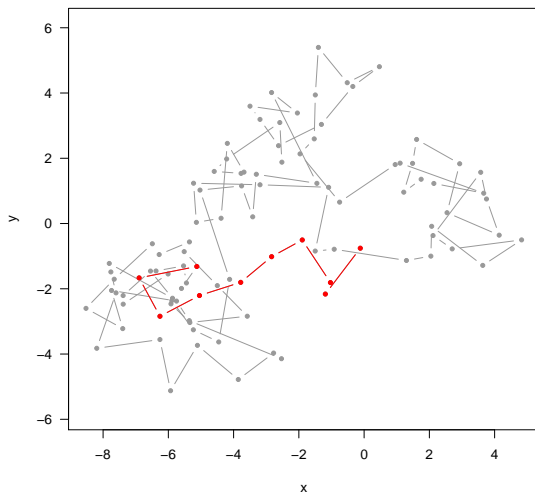
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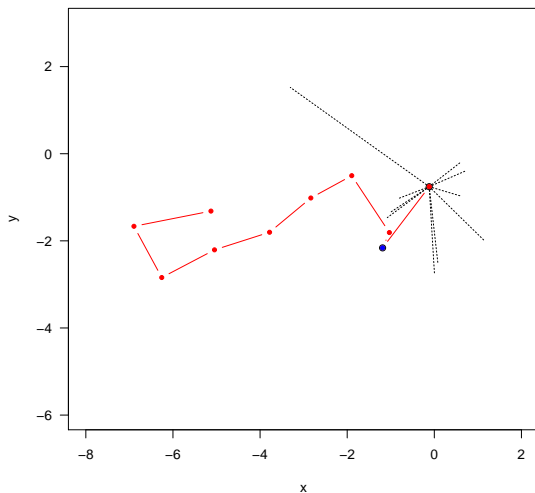
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- Pair each observed step with J random steps.
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- Estimate selection coefficients β with a conditional logistic regression.
- iSSF: including movement related covariates (e.g., step length and turning angles) is equivalent to fitting a biased correlated random walk to the data¹.

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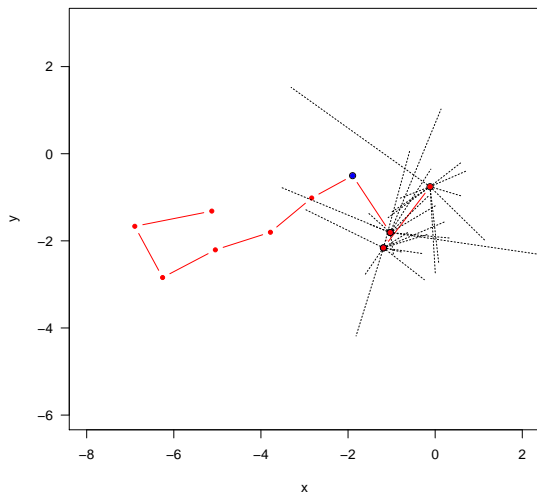
Integrated Step-Selection Functions (iSSF)



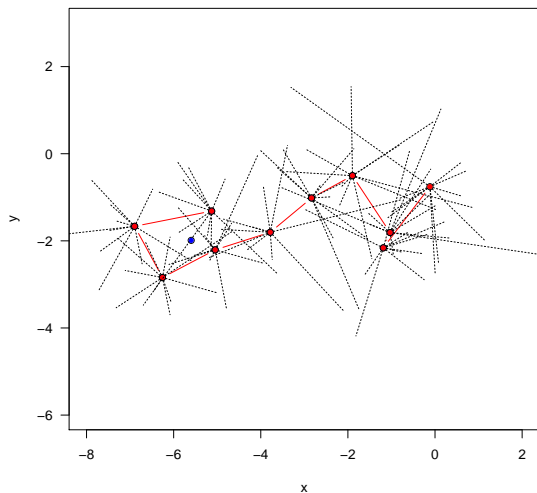
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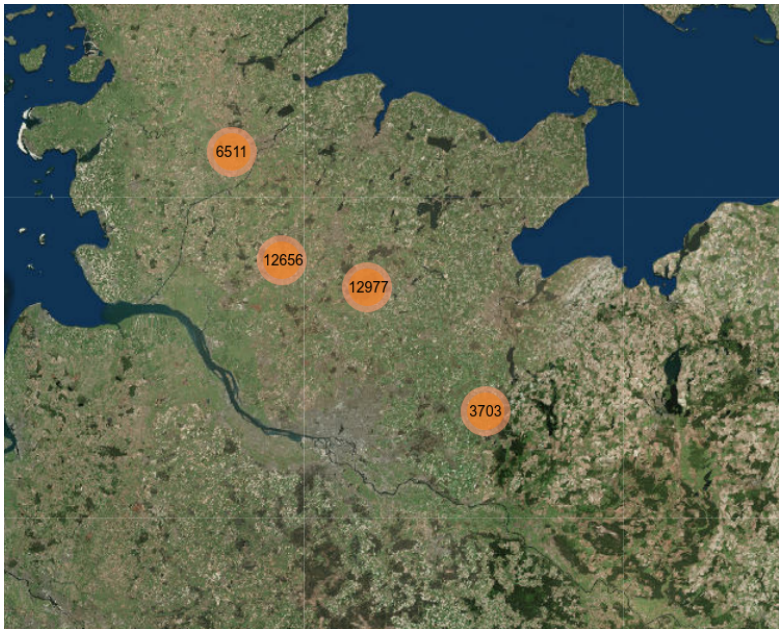


A case study: red deer in Germany

- 24 red deer collared in northern Germany from 2008 to 2013
- 6 hours sampling rate (the number of relocations range from 430 to 3600)
- Each observed step was paired with 9 random steps
- iSSF as mixed Poisson Regression¹ with package amt²

¹Muff, S. et al. (2018). Accounting for individual-specific variation in habitat-selection studies: Efficient estimation of mixed-effects models using Bayesian or frequentist computation. *bioRxiv*, 411801.

²Signer, J. et al. (2018). Animal Movement Tools (amt): R-Package for Managing Tracking Data and Conducting Habitat Selection Analyses. *arXiv preprint arXiv:1805.03227*.



With the following covariates

- Land cover (forest or open)
- Distance to urban areas
- Distance to home-range center
- Step length
- Interactions with time of day

Results

Fixed effects:

Term	Estimate
Forest (time of day = day)	2.36***
Forest (time of day = night)	-3.42***

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Distance to urban (time of day = night)	-0.39**

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Forest (time of day = day)	2.36***
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Distance to urban (time of day = day)	0.26*
Distance to urban (time of day = night)	-0.39**
Distance to center (time of day = day)	-3.36***
Distance to center (time of day = night)	3.28*

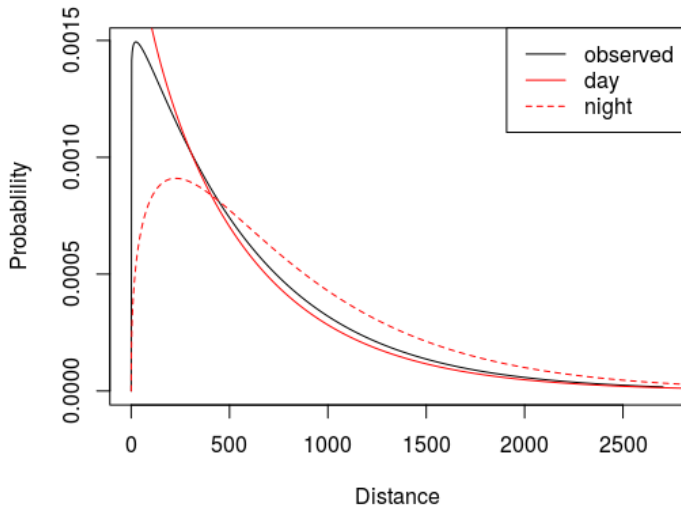
Results

Fixed effects:

Term	Estimate
Forest (time of day = day)	2.36***
Forest (time of day = night)	-3.42***
Distance to urban (time of day = day)	0.26*
Distance to urban (time of day = night)	-0.39**
Distance to center (time of day = day)	-3.36***
Distance to center (time of day = night)	3.28*
log(step length) (time of day = day)	-0.11***
log(step length) (time of day = night)	0.46***

*** $p < 0.001$, ** $p < 0.01$, * $p < 0.05$

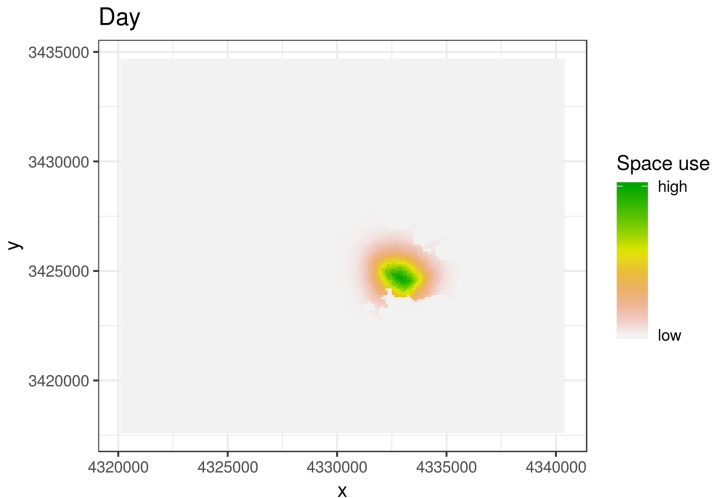
Underlying step-length distribution differs between day and night:



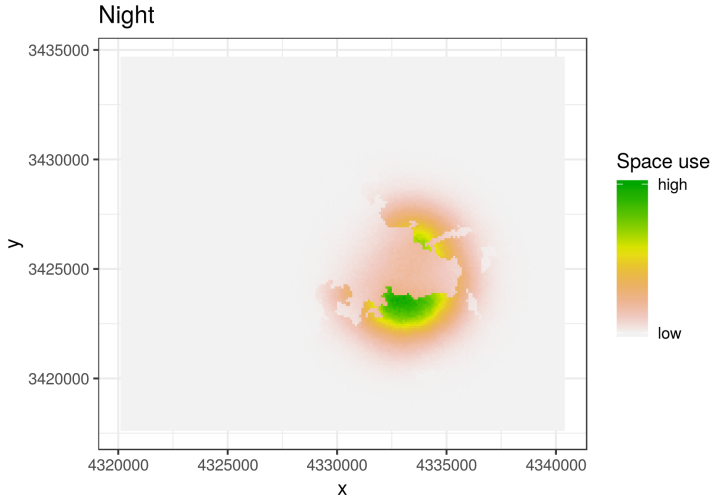
Simulate and predict space use from fitted iSSF

1. A typical animal (fixed effects only)
2. Use random effects of a specific animal
3. For prediction: random effects of a similar animal (in environmental space)

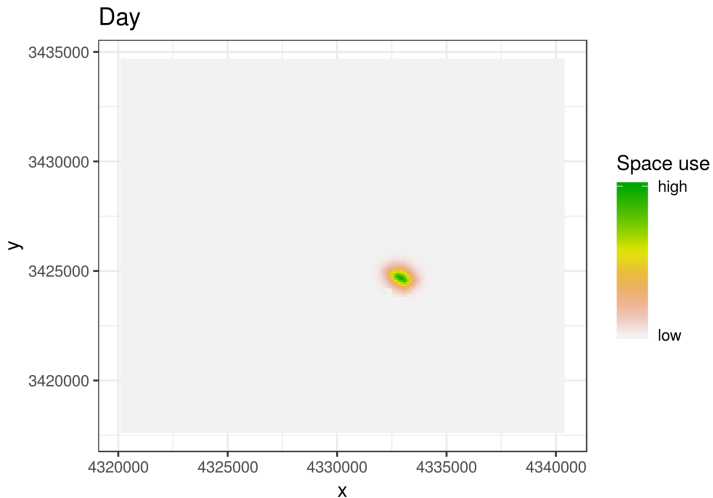
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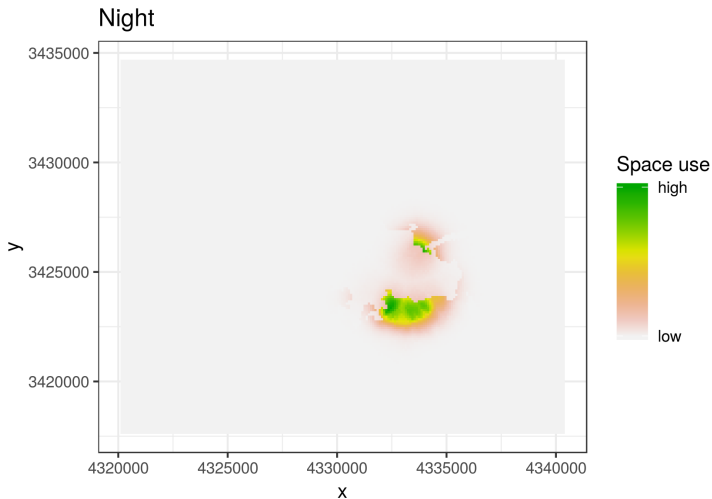
A typical animal (fixed effects only)



This animal (random effects)

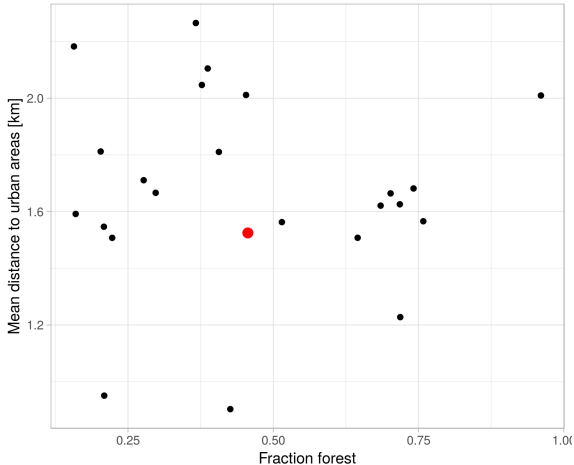


This animal (random effects)

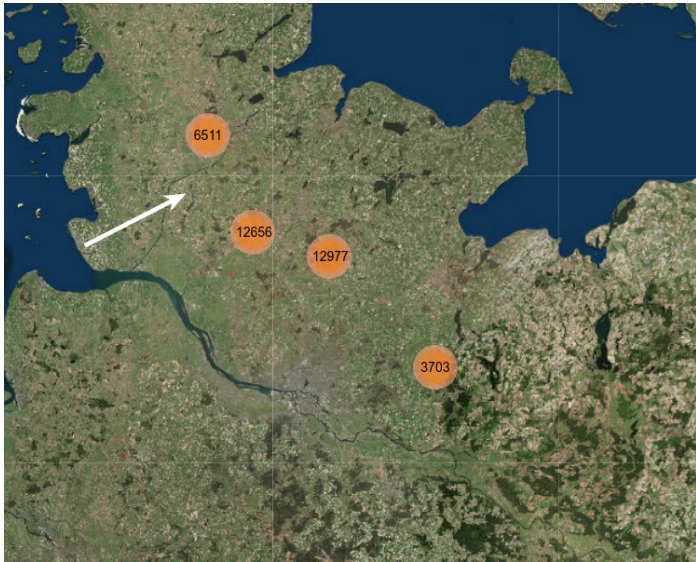


Predict space use in a novel environment

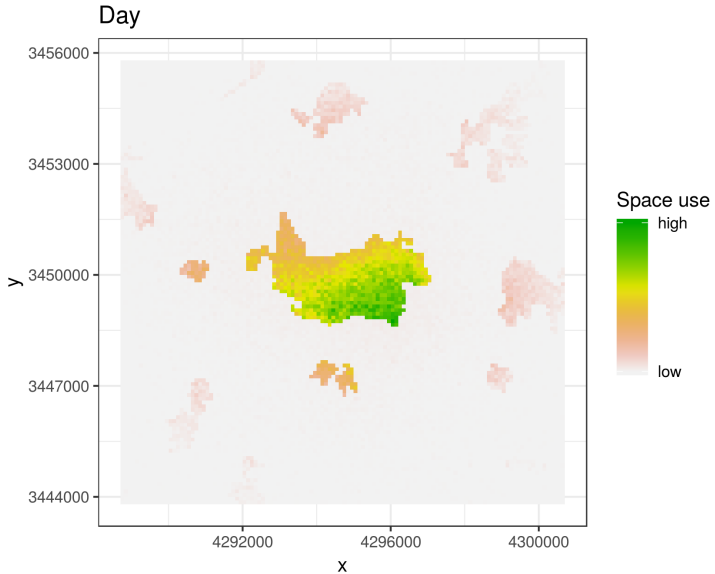
Find animal that is closest to the new environment in environmental space...



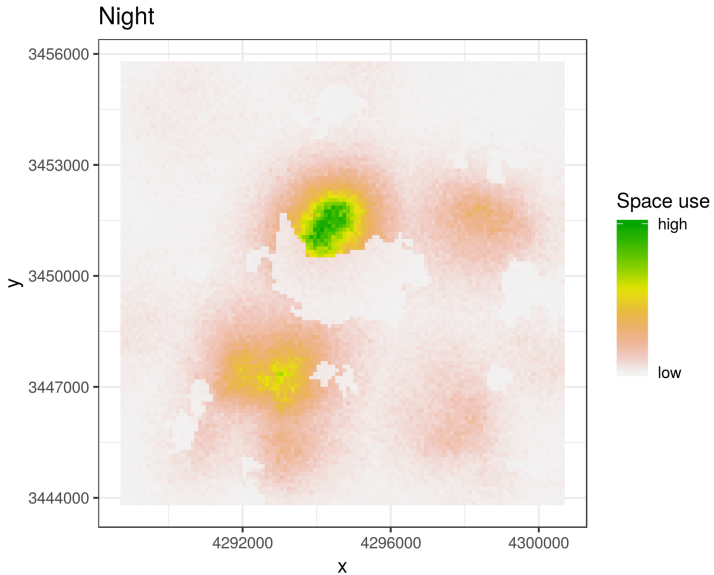
... and predict space use in novel environment.



... and predict space use in novel environment.



... and predict space use in novel environment.



Summary and outlook

- Space use depends on time of day and the environment.
- iSSFs provides a simple but powerful mechanistic movement model, that allows simulations.
- We are working on more sophisticated simulations (time varying covariates).

|

Appendix

$$y_{ntj} = \text{Poisson}(\lambda_{ntj})$$

$$\begin{aligned}\log(\lambda_{ntj}) = & \alpha_{nt} + \beta_{1n}\text{forest} + \beta_{2n}\text{dist_urban} + \beta_{3n}\text{log_sl} \\ & + \beta_{4n}\text{forestnight} + \beta_{5n}\text{dist_urbannight} + \beta_{6n}\text{dist_cent} \\ & + \beta_{7n}\text{log_slnight} + \beta_{8n}\text{dist_cent} \\ & + \beta_{9n}\text{dist_centnight}\end{aligned}$$

With

- $n = 1 \dots N$ individuals
- $t = 1 \dots T_n$ time points (= strata)
- $j = 1 \dots J$ steps per stratum.
- $y_{ntj} = 1$ for observed steps and 0 for random steps.
- $\alpha_{nt} \sim N(0, 10^6)$

Random effects were uncorrelated.